



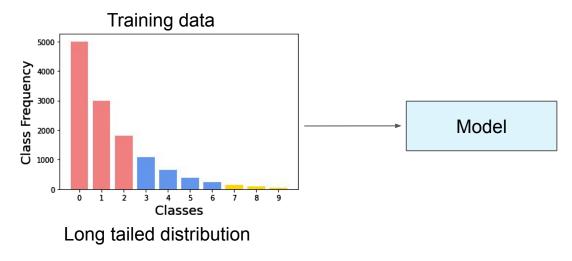
Escaping Saddle Points for Effective Generalization on Class-Imbalanced Data

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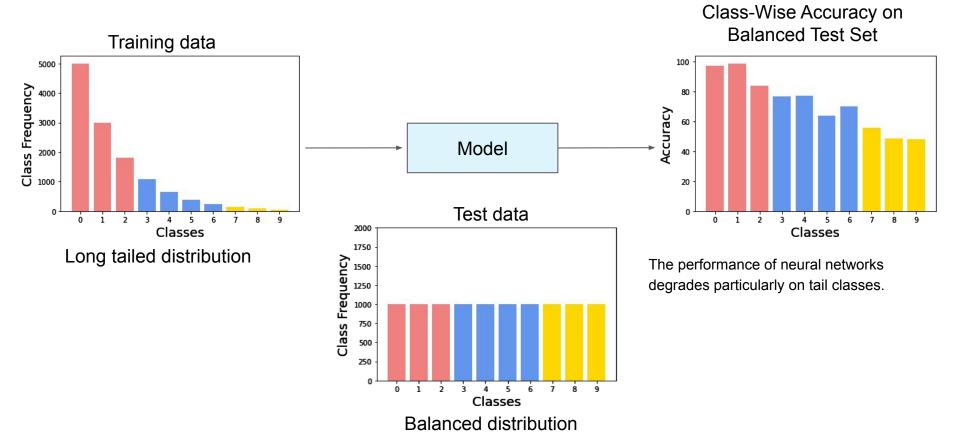
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Long-Tailed Learning



Natural datasets are often imbalanced in terms of the frequency of samples in each class.

Long-Tailed Learning



Long-Tailed Learning

We now discuss some methods based on loss manipulation for imbalance learning:

1. Cross-Entropy + Deferred-Reweighting (CE+DRW)^[1]
Re-weight the CE loss based on the inverse of number of samples in each class. (Minority class samples are given more weight)

^[1]Cao, Kaidi, et al. "Learning Imbalanced Datasets with Label-Distribution-Aware Margin Loss." NeurIPS 2019.

Motivation Analysis Method Results Conclusion

Long-Tailed Learning

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1. Cross-Entropy + Deferred-Reweighting (CE+DRW)^[1]
Re-weight the CE loss based on the inverse of number of samples in each class. (Minority class samples are given more weight)

2. LDAM (Margin Based Loss)^[1]

Regularize the minority class samples more (Larger margin) compared to the majority class samples.

3. **Vector Scaling Loss (VS)**^[2] Combination of Multiplicative (Class Dependent Temperature) and Additive Adjustments (Logit Adjustment)

^[1]Cao, Kaidi, et al. "Learning Imbalanced Datasets with Label-Distribution-Aware Margin Loss." NeurIPS 2019.

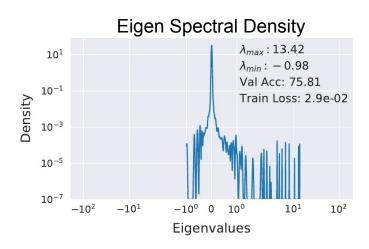
^[2]Kini, Ganesh Ramachandra, et al. "Label-imbalanced and group-sensitive classification under overparameterization." NeurIPS 2021

Loss Landscape

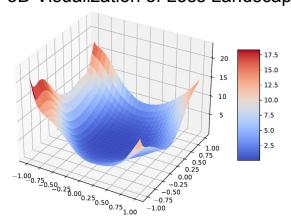
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Loss Landscape

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- Eigenvalues of the Hessian (Eigen Spectral Density) characterize the local curvature of the loss at the solution.



3D Visualization of Loss Landscape



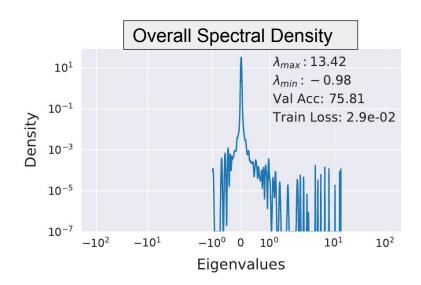
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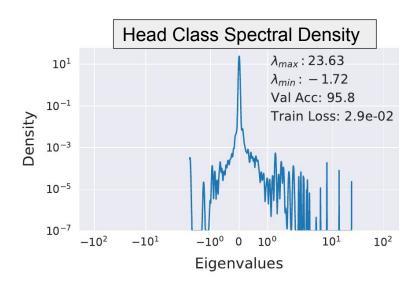
- The Hessian of the training loss can be used to analyze the nature of minima and the dynamics of optimization in deep neural networks.
- Eigenvalues of the Hessian (Eigen Spectral Density) characterize the local curvature of the loss at the solution.
- Geometry of the loss landscape is correlated with generalization. For example, flat minima generalizes better than sharp minima.^[1]

^[1]Keskar, Nitish Shirish, et al. "On large-batch training for deep learning: Generalization gap and sharp minima." ICLR 2017.

Class-Wise Loss Landscape Analysis in Imbalanced Datasets

- **Prior Work**: Hessian of the overall loss is used to characterize the nature of minima.
- On imbalanced datasets, this analysis is not very useful as it indicates convergence to **local minima** and **imitates the head classes**.



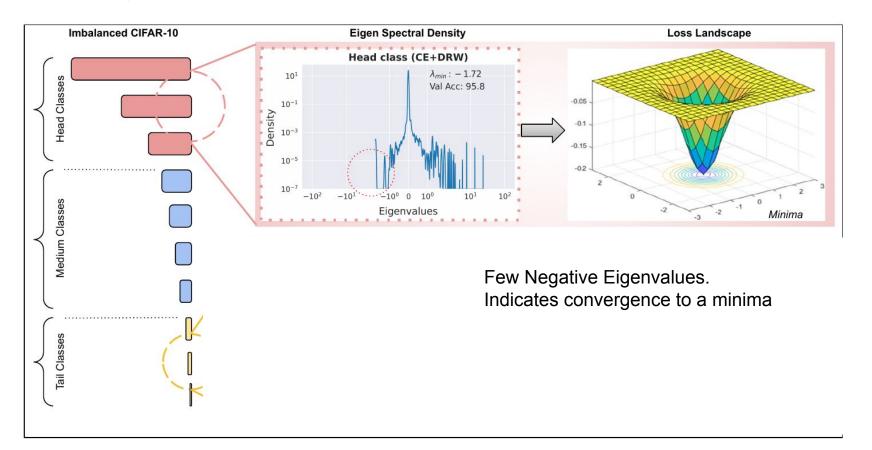


Class-Wise Loss Landscape Analysis in Imbalanced Datasets

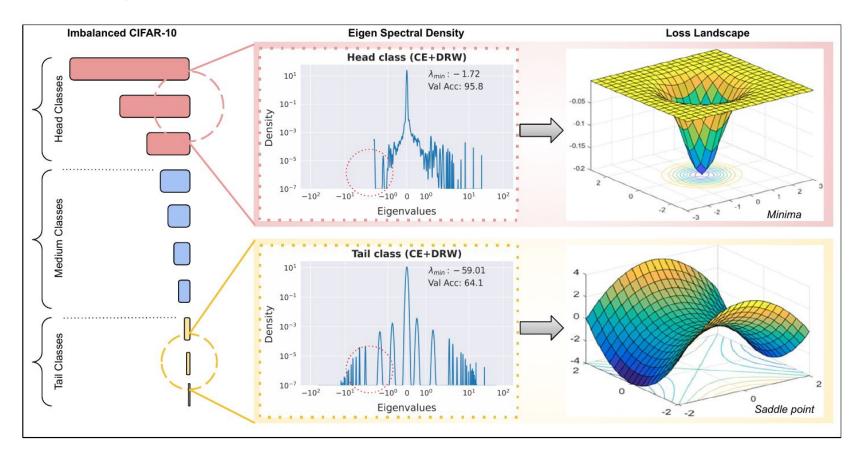
- **Prior Work**: Hessian of the average loss (Eigen Spectral Density) is used to characterize the nature of minima.
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Our work: Class-Wise Analysis of loss landscape on imbalanced datasets uncovers interesting insights.

Convergence to Saddle Points in Tail Class Loss Landscape



Convergence to Saddle Points in Tail Class Loss Landscape



Escaping Saddle Points Improves Generalization

• Due to the occurrence of saddle points, we observe that the network suffers from poor generalization on minority classes.

^[1] Jin, Chi, et al. "How to escape saddle points efficiently." International Conference on Machine Learning. PMLR, 2017.

Motivation Analysis Method Results Conclusion

Escaping Saddle Points Improves Generalization

- Due to the convergence to saddle points, we observe that the network suffers from poor generalization on minority classes.
- Sharpness-Aware Minimization (SAM)^[2] is a recently proposed optimizer with an objective to explicitly find a flat minima with a low loss.
- We show that Sharpness-Aware Minimization (SAM) can also escape saddle points and lead to improved generalization particularly on the tail classes.

^[1]Jin, Chi, et al. "How to escape saddle points efficiently." International Conference on Machine Learning. PMLR, 2017.

^[2] Foret, Pierre, et al. Sharpness-aware minimization for efficiently improving generalization. In ICLR, 2021

Analysis of SAM for Escaping Saddle Points

SAM:

$$\min_{w} \max_{||\epsilon|| < \rho} f(w + \epsilon)$$

f : Objective Function

ρ: Neighborhood size

First step: Find a sharp maximal point ϵ in the neighborhood of the weights w.

Second step: Minimize the loss at this sharp maximal point.

$$\hat{\epsilon}(w) \approx \underset{||\epsilon|| \le \rho}{\operatorname{arg\,max}} f(w) + \epsilon^T \nabla f(w) = \rho \nabla f(w) / ||\nabla f(w)||_2$$

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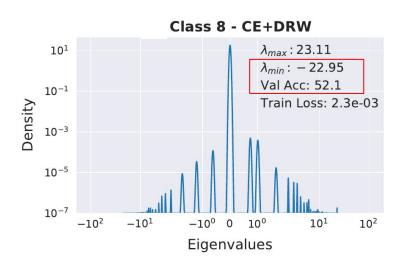
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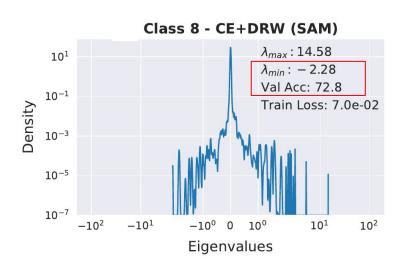
Theoretical Result (Informal):

We theoretically show that the SAM amplifies the gradient component along the negative curvature by a factor of ρ^2 . This helps SAM to effectively escape saddle points.

Escaping Saddle Points Improves Generalization

With SAM (high ρ), the large negative eigenvalues present in the loss landscape of the tail class get suppressed. (i.e no more saddle point)

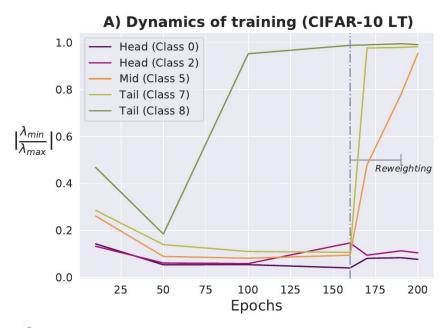




Eigen Spectral Density of **Tail Classes** with SGD (left) and SAM (right)

Dynamics of Training on Long-Tailed datasets

With SGD, network converges to non-convex regions with negative curvature for tail classes.

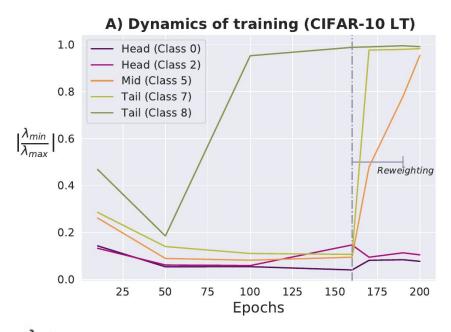


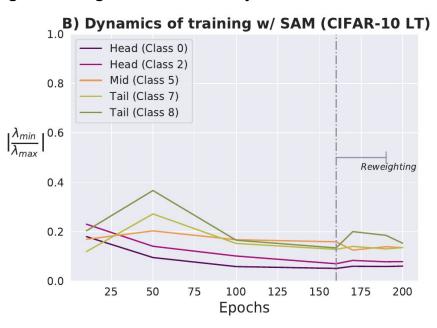
We find that with reweighting and margin enhancement is the main culprit, which forces model into non-convex regions leading to saddle points.

 $\left|\frac{\Lambda_{min}}{\lambda_{max}}\right|$: Measure of non-convexity of the loss landscape. (High value indicates non-convex regions)

Dynamics of Training on Long-Tailed datasets

SAM does not allow the tail classes to reach a region of high non-convexity.





 $\left|\frac{\Lambda_{min}}{\lambda_{max}}\right|$: Measure of non-convexity of the loss landscape. (High value indicates non-convex regions)

Results on CIFAR-10 LT and CIFAR-100 LT

	CIFAR-10 LT				CIFAR-100 LT				
	Acc	Head	Mid	Tail	Acc	Head	Mid	Tail	
CE CE + SAM	$71.7_{\pm 0.1}$ $73.1_{\pm 0.3}$	$90.8_{\pm 3.6} \\ 93.3_{\pm 0.2}$	$71.9_{\pm 0.4}$ $74.1_{\pm 0.6}$	$52.3_{\pm 3.7}$ $51.7_{\pm 1.0}$	$38.5_{\pm 0.5}$ $39.6_{\pm 0.6}$	$64.5_{\pm 0.7}$ $66.5_{\pm 0.7}$	$36.8_{\pm 1.0} \\ 38.1_{\pm 1.1}$		
CE + DRW [8] CE + DRW + SAM	$75.5_{\pm 0.2} \\ 80.6_{\pm 0.4}$	$91.6_{\pm 0.4} \\ 91.4_{\pm 0.3}$		$61.4_{\pm 0.9}$ $73.1_{\ \pm 0.9}$			$41.7_{\pm 0.5}$ $47.5_{\pm 0.6}$		

5.1%

3.6%

DRW + SAM improves upon the overall performance of CE+DRW by 5.1% on CIFAR-10 LT and 3.6% on CIFAR-100 LT datasets, with the tail class accuracy increasing by 11.7% and 7.7% respectively.

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CE + DRW [8] CE + DRW + SAM	$75.5_{\pm 0.2} \\ 80.6_{\pm 0.4}$	$91.6_{\pm 0.4} \\ 91.4_{\pm 0.3}$	$74.1_{\pm 0.4} \\ 78.0_{\pm 0.4}$	$61.4_{\pm 0.9}$ $73.1_{\ \pm 0.9}$	$41.0_{\pm 0.6}$ $44.6_{\pm 0.4}$	$61.3_{\pm 1.3} $ $61.2_{\pm 0.8}$	$41.7_{\pm 0.5}$ $47.5_{\pm 0.6}$	$14.7_{\pm 0.9} \\ 20.7_{\pm 0.6}$	
LDAM + DRW [8] LDAM + DRW + SAM	$77.5_{\pm 0.5}$ $81.9_{\pm 0.4}$	$91.1_{\pm 0.8} \\ 91.0_{\pm 0.2}$	$75.7_{\pm 0.7} \\ 79.2_{\pm 0.5}$	$66.4_{\pm 0.2}$ $76.4_{\ \pm 1.1}$	$42.7_{\pm 0.3}$ $45.4_{\pm 0.1}$	$61.8_{\pm 0.6}$ $64.4_{\pm 0.3}$	$42.2_{\pm 1.5} \\ 46.2_{\pm 0.2}$	$19.4_{\pm 0.9} \\ 20.8_{\ \pm 0.3}$	
VS [30] VS + SAM	$78.6_{\pm 0.3}$ $82.4_{\pm 0.4}$	$90.6_{\pm 0.4}$ $90.7_{\pm 0.0}$	$75.8_{\pm 0.5} \\ 79.6_{\pm 0.5}$	$70.3_{\pm 0.5} \\ 78.0_{\pm 01.2}$	$\begin{array}{c c} 41.7_{\pm 0.5} \\ 46.6_{\pm 0.4} \end{array}$	$54.4_{\pm 0.2}$ $56.4_{\pm 0.4}$	$41.1_{\pm 0.6}$ $48.8_{\pm 0.6}$	$26.8_{\pm 1.0} \\ 31.7_{\pm 0.1}$	

Integrating SAM with state-of-the-art techniques for long-tailed learning (LDAM, VS) leads to significant gains in overall accuracy primarily due to the major gain in the accuracy on the tail classes.

Results on Large Scale Datasets

- Problem of saddle points also exists in large datasets.
- SAM is easily generalizable to large-scale imbalanced datasets without any changes.

Method	19	iNatural	ist 2018	}	ImageNet-LT				
	Two stage	Acc	Head	Mid	Tail	Acc	Head	Mid	Tail
CE	×	60.3	72.8	62.7	54.8	42.7	62.5	36.6	12.5
cRT [27] †	✓	68.2	<u>73.2</u>	68.8	66.1	50.3	62.5	47.4	29.5
LWS [27] †	✓	69.5	71.0	69.8	68.8	51.2	61.8	48.6	33.5
MiSLAS [57]	/	71.6	<u>73.2</u>	72.4	<u>70.4</u>	52.7	61.7	51.3	35.8
DisAlign [55]	/	69.5	61.6	70.8	69.9	52.9	61.3	52.2	31.4
DRO-LT [44]	×	69.7	73.9	70.6	68.9	53.5	64.0	49.8	33.1
CE + DRW	×	63.0	59.8	64.4	62.3	44.9	57.9	42.2	21.6
CE + DRW + SAM	×	65.3	60.5	66.2	65.5	47.1	56.6	45.8	28.1
LDAM + DRW	×	67.5	63.0	68.3	67.8	49.9	61.1	48.2	28.3
LDAM + DRW + SAM	×	<u>70.1</u>	64.1	70.5	71.2	<u>53.1</u>	62.0	<u>52.1</u>	<u>34.8</u>

Summary and Conclusion

1. Training on imbalanced datasets can lead to convergence to points with sufficiently large negative curvature in the loss landscape for minority classes.

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- 1. Training on imbalanced datasets can lead to convergence to points with sufficiently large negative curvature in the loss landscape for minority classes.
- We propose to use SAM with a high regularization factor ρ as an effective method to escape regions of negative curvature and enhance the generalization performance.

Summary and Conclusion

- 1. Training on imbalanced datasets can lead to convergence to points with sufficiently large negative curvature in the loss landscape for minority classes.
- 2. We propose to use **SAM** with a high regularization factor ρ as an effective method to escape regions of negative curvature and **enhance the generalization performance**.
- 3. Results on various datasets with different long-tail learning methods indicate that the proposed method is **generic** and **improves performance** significantly.

Thank You

